

1. Necht  $u$ , resp.  $\vec{f}$  označuje skalární, resp. vektorovou funkci třídy  $C^1$ . Použitím rozkladu (dále naznačeného dolními vodorovnými svorkami) podle pravidla

$$\operatorname{div}(u\vec{f}) = u\operatorname{div}\vec{f} + \vec{f} \cdot \nabla u$$

vypočítejte divergenci pole elektrické indukce ( $E$  je konstantní veličina)

$$\vec{D} = \frac{E}{\|\vec{r}\|^3} \vec{r} = \frac{E}{\sqrt{(x^2 + y^2 + z^2)^3}} (x\vec{i} + y\vec{j} + z\vec{k})$$

Vektor elektrické indukce můžeme rozdělit na skalární část  $u$  a vektorovou část  $\vec{f}$ .

$$u = \frac{E}{\sqrt{(x^2 + y^2 + z^2)^3}} \quad a \quad \vec{f} = (x\vec{i} + y\vec{j} + z\vec{k})$$

Do zadaného vztahu potřebujeme  $\operatorname{div}\vec{f}$  (divergenci vektorové funkce  $f$ ) a  $\nabla u$  (gradient skalární funkce  $u$ ).

Dle definice  $\vec{f} = P\vec{i} + Q\vec{j} + R\vec{k}$  je divergence rovna:

$$\operatorname{div}\vec{f} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

a gradient skalární funkce  $u$ :

$$\nabla u = \frac{\partial u}{\partial x} \vec{i} + \frac{\partial u}{\partial y} \vec{j} + \frac{\partial u}{\partial z} \vec{k}.$$

Tedy pro naše zadání je  $\operatorname{div}\vec{f}$  a  $\nabla u$ :

$$\operatorname{div}\vec{f} = (1 + 1 + 1)$$

$$\frac{\partial u}{\partial x} = \frac{-3E}{2}(x^2 + y^2 + z^2)^{-\frac{5}{2}} 2x \quad \frac{\partial u}{\partial y} = \frac{-3E}{2}(x^2 + y^2 + z^2)^{-\frac{5}{2}} 2y \quad \frac{\partial u}{\partial z} = \frac{-3E}{2}(x^2 + y^2 + z^2)^{-\frac{5}{2}} 2z$$

$$\nabla u = -3E(x^2 + y^2 + z^2)^{-\frac{5}{2}} x\vec{i} + -3E(x^2 + y^2 + z^2)^{-\frac{5}{2}} y\vec{j} + -3E(x^2 + y^2 + z^2)^{-\frac{5}{2}} z\vec{k}$$

$$\nabla u = -3E \frac{1}{\sqrt{(x^2 + y^2 + z^2)^5}} (x\vec{i} + y\vec{j} + z\vec{k})$$

Doplníme do předpisu:

$$\operatorname{div}(u\vec{f}) = \frac{E}{\sqrt{(x^2 + y^2 + z^2)^3}} \cdot 3 + (x\vec{i} + y\vec{j} + z\vec{k}) \cdot \frac{-3E}{\sqrt{(x^2 + y^2 + z^2)^5}} (x\vec{i} + y\vec{j} + z\vec{k})$$

$$\operatorname{div}(u\vec{f}) = \frac{3E}{\sqrt{(x^2 + y^2 + z^2)^3}} + \frac{-3E}{\sqrt{(x^2 + y^2 + z^2)^5}} (x\vec{i} + y\vec{j} + z\vec{k})^2$$

$$\operatorname{div}(u\vec{f}) = \frac{3E}{\sqrt{(x^2 + y^2 + z^2)^3}} - \frac{3E}{(x^2 + y^2 + z^2)\sqrt{(x^2 + y^2 + z^2)^3}}(x\vec{i} + y\vec{j} + z\vec{k})^2$$

POZN:

$$\vec{i} \cdot \vec{i} = (1, 0, 0)(1, 0, 0) = 1 + 0 + 0 = 1$$

$$\vec{j} \cdot \vec{j} = (0, 1, 0)(0, 1, 0) = 0 + 1 + 0 = 1$$

$$\vec{i} \cdot \vec{j} = (1, 0, 0)(0, 1, 0) = 0 + 0 + 0 = 0$$

$$\vec{j} \cdot \vec{k} = (0, 1, 0)(0, 0, 1) = 0 + 0 + 0 = 0 \text{ atd.}$$

$$\operatorname{div}(u\vec{f}) = \frac{3E}{\sqrt{(x^2 + y^2 + z^2)^3}} - \frac{3E}{(x^2 + y^2 + z^2)\sqrt{(x^2 + y^2 + z^2)^3}}(x^2 + y^2 + z^2)$$

$$\operatorname{div}(u\vec{f}) = \frac{3E}{\sqrt{(x^2 + y^2 + z^2)^3}} - \frac{3E}{\sqrt{(x^2 + y^2 + z^2)^3}} = 0$$

Divergence pole je rovna nule, jedaná se o pole neřídlové.

2. Operátorovým počtem dokažte, že pro funkce třídy  $C^2$  platí  $\operatorname{rotgrad}u = \vec{0}$  a  $\operatorname{divrot}\vec{f} = 0$ .

$$\begin{aligned} \operatorname{rotgrad}u &= \operatorname{rot} \left( \frac{\partial u}{\partial x} \vec{i} + \frac{\partial u}{\partial y} \vec{j} + \frac{\partial u}{\partial z} \vec{k} \right) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \end{vmatrix} = \\ &= \left[ \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial z} \right) - \frac{\partial}{\partial z} \left( \frac{\partial u}{\partial y} \right) \right] \vec{i} + \left[ \frac{\partial}{\partial z} \left( \frac{\partial u}{\partial x} \right) - \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial z} \right) \right] \vec{j} + \left[ \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial y} \right) - \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} \right) \right] \vec{k} = \\ &= \left[ \frac{\partial^2 u}{\partial z \partial y} - \frac{\partial^2 u}{\partial y \partial z} \right] \vec{i} + \left[ \frac{\partial^2 u}{\partial x \partial z} - \frac{\partial^2 u}{\partial z \partial x} \right] \vec{j} + \left[ \frac{\partial^2 u}{\partial y \partial x} - \frac{\partial^2 u}{\partial x \partial y} \right] \vec{k} = 0\vec{i} + 0\vec{j} + 0\vec{k} = \vec{0} \end{aligned}$$

$$\begin{aligned} \operatorname{divrot}\vec{f} &= \operatorname{div} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \operatorname{div} \left[ \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k} \right] = \\ &= \left[ \frac{\partial}{\partial x} \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) + \frac{\partial}{\partial y} \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) + \frac{\partial}{\partial z} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \right] = \\ &= \left( \frac{\partial^2 R}{\partial y \partial x} - \frac{\partial^2 Q}{\partial z \partial x} + \frac{\partial^2 P}{\partial z \partial y} - \frac{\partial^2 R}{\partial x \partial y} + \frac{\partial^2 Q}{\partial x \partial z} - \frac{\partial^2 P}{\partial y \partial z} \right) = 0 \end{aligned}$$

3.

$$\vec{f} = \left( \frac{x}{x^2 + y^2 + 1}; \frac{y}{x^2 + y^2 + 1}; 3z \right)$$

Jestliže mluvíme o poli konzervativním, pak je jeho  $\text{rot } \vec{f} = 0$ . Dle definice jsou funkce  $P = \frac{x}{x^2+y^2+1}$ ,  $Q = \frac{y}{x^2+y^2+1}$ ,  $R = 3z$ .

$$\text{rot } \vec{f} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = \left[ \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k} \right]$$

$$\frac{\partial R}{\partial y} = 0 \quad \frac{\partial Q}{\partial z} = 0 \quad \frac{\partial P}{\partial z} = 0 \quad \frac{\partial R}{\partial x} = 0 \quad \frac{\partial Q}{\partial x} = \frac{-2xy}{(x^2 + y^2 + 1)^2} \quad \frac{\partial P}{\partial y} = \frac{-2xy}{(x^2 + y^2 + 1)^2}$$

po dosazení do zadání obdržíme vztah:

$$= \left[ (0 - 0) \vec{i} + (0 - 0) \vec{j} + \left( \frac{-2xy}{(x^2 + y^2 + 1)^2} + \frac{2xy}{(x^2 + y^2 + 1)^2} \right) \vec{k} \right] = 0\vec{i} + 0\vec{j} + 0\vec{k} = \vec{0}$$

4.